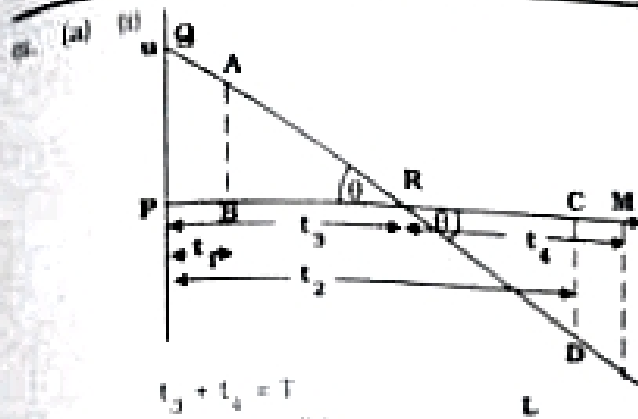




$$t_3 + t_4 = T$$

$$\tan \theta = \frac{PQ}{PR} \Rightarrow g = \frac{u}{t_3}$$

$$t_3 = \frac{u}{g} \therefore PQR \Delta = \frac{u^2}{2g}$$

$$\therefore RML \Delta = \frac{u^2}{2g} \text{ also}$$

$$\tan \theta = \frac{ML}{t_4} = g$$

$$RML \Delta = \frac{1}{2} t_4 \cdot g t_4 = \frac{u^2}{2g}$$

$$t_4^2 = \frac{u^2}{g^2} \Rightarrow t_4 = \frac{u}{g}$$

$$\therefore t_3 = t_4 = \frac{u}{g} \text{ and } T = \frac{2u}{g}$$

Now in $\triangle PQR$ and $\triangle RML$

$$BR = \frac{u}{g} - t_1$$

$$RC = t_2 \cdot \frac{u}{g} \left[\because PR = \frac{u}{g} \right]$$

t_1 and t_2 are the times taken by the projectile to reach points B and C respectively.

$$ABR \Delta = RCD \Delta$$

$$\therefore BR = RC$$

$$\therefore \frac{1}{2} BR \cdot g \cdot BR = \frac{1}{2} RC \cdot g \cdot RC$$

$$AB = g \cdot BR \Rightarrow CD = g \cdot RC$$

$$\frac{u}{g} - t_1 = t_2 - \frac{u}{g} \Rightarrow$$

$$t_1 + t_2 = \frac{2u}{g} = T$$

(ii) $(A E) = \uparrow V$; $(B E) = \nearrow u$

$(C E) = \nearrow u$; $(B A) = \nwarrow u$

$(C A) = \nearrow \alpha$

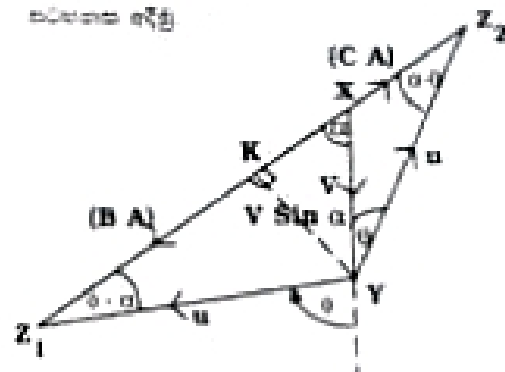
$$(B A) = (B E) + (E A)$$

$$\begin{aligned} \nwarrow u &= \nearrow u + \uparrow V \\ &= \uparrow V + \nearrow u \\ &= XY + YZ_1 \\ &= XZ_1 \end{aligned}$$

$$(C A) = (C E) + (E A)$$

$$\begin{aligned} \nearrow \alpha &= \nearrow u + \uparrow V \\ &= \uparrow V + \nearrow u \\ &= XY + YZ_2 \\ &= XZ_2 \end{aligned}$$

(b) XYZ_1 and XYZ_2 are right-angled triangles with the right angle at Y.



(i) XYZ_1 is a right-angled triangle with the right angle at Y.

$$\frac{U}{\sin \alpha} = \frac{V}{\sin (\theta - \alpha)} \quad \text{--- (1)}$$

and XYZ_2 is

$$\frac{U}{\sin (\pi - \alpha)} = \frac{V}{\sin (\alpha + \theta)} \quad \text{--- (2)}$$

From (1) and (2)

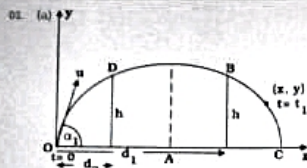
$$\frac{U}{\sin \alpha} = \frac{V}{\sin (\theta - \alpha)} = \frac{V}{\sin (\alpha + \theta)}$$

$$(B C) = (B A) + (A C) = 0$$

$$\begin{aligned} &= XZ_1 + (-XZ_2) \\ &= XZ_1 + Z_2 X = Z_2 Z_1 \end{aligned}$$

$$YZ_1 Z_2 \Delta \text{ is } Z_1 Z_2 = 2(Z_1 K)$$

$$= 2 \sqrt{u^2 - V^2 \sin^2 \alpha} \text{ (KYZ}_1 \Delta \text{ is)}$$



O සහ C දී x, y දෘශ්‍ය අනු ඔර්වයන් සිට
සම්බන්ධතා සොයා

$$\rightarrow x = u \cos \alpha_1 t_1 \quad \text{--- ①}$$

$$\uparrow y = u \sin \alpha_1 t_1 - \frac{1}{2} g t_1^2 \quad \text{--- ②}$$

(1) හි දී \$t_1\$ අගය ඔර්වයන්

$$y = x \tan \alpha_1 - \frac{g x^2}{2 u^2 \cos^2 \alpha_1} \quad \text{--- ③}$$

③ සම්බන්ධතා සොයා බලා

$$g x^2 \sec^2 \alpha_1 - 2 u^2 x \tan \alpha_1 + 2 u^2 y = 0$$

මෙය x හි ද්විතීයික සමීකරණයකි.

$$y = h \text{ වීම සම්බන්ධ}$$

$$x = d_1 \text{ හා } x = d_2 \text{ වේ. } \therefore D = (d_2, h)$$

$$B = (d_1, h)$$

$$\text{③ හි } x_1 + x_2 = \frac{2 u^2 \tan \alpha_1}{g \sec^2 \alpha_1} = \frac{u^2}{g} \sin 2 \alpha_1$$

$$\therefore d_1 + d_2 = \frac{u^2}{g} \sin 2 \alpha_1 \quad \text{--- ④}$$

$$x_1 x_2 = \frac{2 u^2 h}{g \sec^2 \alpha_1} = \frac{2 h u^2}{g} \cos^2 \alpha_1$$

$$= d_1 d_2 \text{ වේ}$$

$$h \leq \frac{u^2}{2g} \sin^2 \alpha_1 \text{ බැවින් } d_1 \text{ හා } d_2 \text{ අයත්}$$

$$\text{සමීකරණයේ } d_1 = d_2 \text{ වේ. } \therefore x_1 = x_2 \Rightarrow d_1 = d_2$$

$$\text{එවිට ④ හි } 2 d_1 = \frac{u^2 \sin 2 \alpha_1}{g} \Rightarrow$$

$$d_1 = \frac{u^2 \sin 2 \alpha_1}{2g} = OA$$

මෙය \$u_2\$ වීම Q අග්‍රයේ OA, ඔරු දිශාවේ

$$\text{එවිට උසට උසස්ම බැවින් } OA = \frac{u^2 \sin 2 \alpha_2}{2g}$$

වේ.

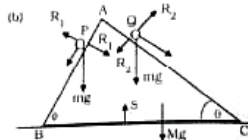
$$\text{එවිට } \frac{u^2 \sin 2 \alpha_1}{2g} = \frac{u^2 \sin 2 \alpha_2}{2g}$$

$$\Rightarrow \sin 2 \alpha_1 = \sin 2 \alpha_2$$

$$\sin 2 \alpha_1 = \sin (\pi - 2 \alpha_2)$$

$$\Rightarrow 2 \alpha_1 = \pi - 2 \alpha_2 \Rightarrow \alpha_1 + \alpha_2 = \frac{\pi}{2}$$

$$\therefore \alpha_1 < \frac{\pi}{2} \text{ හා } \alpha_2 < \frac{\pi}{2} \text{ වීමට}$$



$$(P) \text{ වේ } = \frac{a_1}{g}$$

$$(Q) \text{ වේ } = \frac{a_2}{g}$$

$$(R) \text{ වේ } = \frac{a_3}{g}$$

$$(P) \text{ වේ } = (P) \text{ වේ } + (R) \text{ වේ}$$

$$= \frac{a_1}{g} + \frac{a_2}{g} \rightarrow f_1$$

$$(Q) \text{ වේ } = \frac{a_3}{g} \rightarrow f_2$$

$$F = m g \cdot \frac{a_1}{g} + \frac{a_2}{g} \text{ වේ}$$

$$P = m g \sin \theta = m (a_1 - f_1 \cos \theta) \quad \text{--- ①}$$

$$Q = m g \sin \theta = m (a_2 + f_1 \cos \theta) \quad \text{--- ②}$$

$$\text{අන්තර්ගත වෙනසෙන් } f_1 = 0 \text{ වේ}$$

$$\text{① හි } a_1 = g \sin \theta \text{ ද ② හි } a_2 = g \sin \theta \text{ ද වේ.}$$

$$\text{අන්තර්ගත වෙනසෙන් } E = m g$$

$$\rightarrow 0 = M f_1 + m (f_1 + a_2 \cos \theta) +$$

$$m (f_1 - a_1 \cos \theta) \quad \text{--- ③}$$

$$\text{③ හි } a_1 = g \sin \theta + f_1 \cos \theta \text{ වේ}$$

$$\text{③ හි } a_2 = g \sin \theta - f_1 \cos \theta \text{ වේ}$$

$$\text{③ හි } 0 = f_1 (M + 2m) + m \cos \theta$$

$$(g \sin \theta - f_1 \cos \theta) - m \cos \theta (g \sin \theta + f_1 \cos \theta)$$

$$m g (\sin \theta \cos \theta - \sin \theta \cos \theta) =$$

$$f_1 [M + 2m - m \cos^2 \theta - m \cos^2 \theta]$$

$$\frac{m g}{2} [\sin 2 \theta - \sin 2 \theta]$$

$$\frac{m g}{2} [\sin 2 \theta - \sin 2 \theta]$$

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$$\frac{m g}{2} [\sin 2 \theta - \sin 2 \theta]$$

$$\frac{m g}{2} [\sin 2 \theta - \sin 2 \theta]$$

$$= f_1 [M + m (1 - \cos^2 \theta) + m (1 - \cos^2 \theta)]$$

$$= f_1 [M + m (\sin^2 \theta + \sin^2 \theta)]$$

$$f_1 = \frac{m g}{2} \frac{(\sin 2 \theta - \sin 2 \theta)}{[M + m (\sin^2 \theta + \sin^2 \theta)]}$$

$$= 0 \text{ වේ. } 2 \theta = 2 \theta \text{ වේ}$$

$$\sin 2 \theta - \sin 2 \theta = 0$$

$$\therefore f_1 = 0 \text{ වේ. අන්තර්ගත වෙනසෙන් } E = m g$$

$$\text{එවිට } P \text{ හා } Q \text{ හි අන්තර්ගත වෙනසෙන් } E = m g \sin \theta$$

$$= m g \sin \theta \text{ වේ. එවිට}$$

$$= m g \sin \theta \text{ වේ. එවිට}$$

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$$= m g \sin \theta \text{ වේ. එවිට}$$

$$= m g \sin \theta \text{ වේ. එවිට}$$

$$u_1 = \frac{u(e-1) + v(1+e)}{2} > 0 \text{ වීම සඳහා: මෙ}$$

$$\text{සඳහා}$$

$$e(u+v) > u-v \Rightarrow e > \frac{u-v}{u+v} \text{ විය යුතුය.}$$

$$\text{අදහස් වන්නේ } P \text{ හා } Q \text{ සම්බන්ධ නම් දුර්වලතම}$$

$$\text{අග්‍රය}$$

$$I = \frac{2na}{u_1 + v_1} \text{ වේ}$$

$$e(u+v) = v_1 + u_1 \text{ වේ}$$

$$I_1 = \frac{2na}{e(u+v)}$$

$$\text{එවිට අදහස් වන්නේ } I \text{ හි අගය}$$

$$= \frac{2na}{u+v} + \frac{2na}{e(u+v)}$$

$$= \frac{2na}{(u+v)} \left(\frac{1+e}{e} \right)$$

$$= \frac{2na}{(u+v)} \left(\frac{1+e}{e} \right)$$

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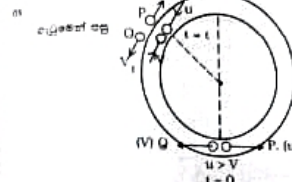
$$= \frac{2na}{(u+v)} \left(\frac{1+e}{e} \right)$$

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$$(a) \text{ P හා Q සම්බන්ධ වෙනසෙන් } E_1 \text{ හා } E_2 \text{ වේ}$$

$$u_1 = \frac{u}{a} \text{ වේ. } u_2 = \frac{v}{a} \text{ වේ}$$

$$I \text{ නිසා } u_1 \text{ හා } u_2 \text{ වේ.}$$

$$u_1 t + u_2 t = 2\pi \text{ (මෙහිදී } 2\pi \text{ වෙනසෙන්)}$$

$$\text{එවිට } t = \frac{2\pi}{u_1 + u_2}$$

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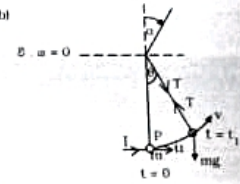
$$t = \frac{2\pi}{u_1 + u_2}$$

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$$t = \frac{2\pi}{u_1 + u_2}$$

$$t = \frac{2\pi}{u_1 + u_2}$$



$$P \text{ හි අන්තර්ගත වෙනසෙන්}$$

$$\rightarrow I = A \text{ (mm)} \text{ වේ}$$

$$I = mu - m(0) \Rightarrow u = \frac{I}{m} \text{ වේ. P හි අන්තර්ගත වෙනසෙන්}$$

$$\text{මෙහිදී } u \text{ හා } I \text{ වේ. එවිට}$$

$$\frac{1}{2} m u^2 - m g a = \frac{1}{2} m v^2 - m g a \cos \theta$$

$$v^2 = u^2 - 2 g a (1 - \cos \theta) = \frac{I^2}{m^2} - 2 g a + 2 g a \cos \theta$$

$$E = m g \quad \text{--- ①}$$

$$T - m g \cos \theta = m \frac{v^2}{a}$$

$$T = \frac{m}{a} [u^2 - 2 g a + 2 g a \cos \theta] + m g \cos \theta$$

$$= \frac{m}{a} \left[\frac{I^2}{m^2} - 2 g a + 2 g a \cos \theta \right]$$

$$T = \frac{I^2}{m a} - 2 m g + 2 m g \cos \theta \quad \text{--- ②}$$

$$T = \frac{I^2}{m a} - 2 m g + 2 m g \cos \theta$$

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$$T = \frac{I^2}{m a} - 2 m g + 2 m g \cos \theta$$

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$$T = \frac{$$

