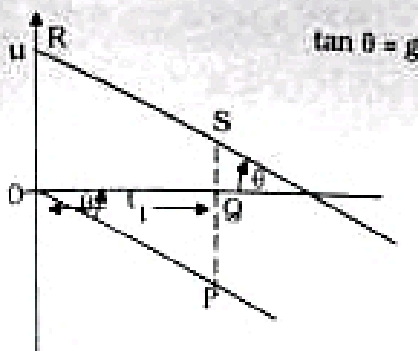


8. (a)



എ-യു രേഖാ രേഖാശാലയിൽ നിന്ന് രണ്ടാം ധ്രുവത്തിൽ എത്തിക്കൽ
A എ-യു രേഖാശാലയിൽ നിന്ന് രണ്ടാം ധ്രുവത്തിൽ എത്തിക്കൽ
(OPQ Δ) ന്റെ B എ-യു രേഖാശാലയിൽ നിന്ന് രണ്ടാം ധ്രുവത്തിൽ എത്തിക്കൽ
(ORSQ Δ) ന്റെ h ന്റെ രേഖാശാലയിൽ എത്തിക്കൽ
അതുകൊണ്ട് $t = t_1$ (OQ) ന്റെ രേഖാശാലയിൽ

$$ORSQ \Delta + OPQ \Delta = ORSP \Delta$$

$$ORSP \Delta = OR \times OQ$$

$$\therefore h = u \times t_1 \Rightarrow t_1 = \frac{h}{u}$$

$$(b) (w, d) = \begin{matrix} \nearrow \\ \searrow \end{matrix} u, (w, d) = w$$

$$(w, d, w_1) = (w, d, w) + (d, w_1)$$

$$= \begin{matrix} \nearrow \\ \searrow \end{matrix} w + \begin{matrix} \nearrow \\ \searrow \end{matrix} u$$

$$= \begin{matrix} \nearrow \\ \searrow \end{matrix} w \cos \theta + \begin{matrix} \nearrow \\ \searrow \end{matrix} u$$

$$(w, d, w_1) = \rightarrow (w \sin \theta - u) + \uparrow (w \cos \theta - v)$$

രേഖാശാലയിൽ നിന്ന് രേഖാശാലയിൽ നിന്ന് രേഖാശാലയിൽ

രേഖാശാലയിൽ നിന്ന് രേഖാശാലയിൽ നിന്ന് രേഖാശാലയിൽ

രേഖാശാലയിൽ, $w \sin \theta - u = 0$ ന്റെ രേഖാശാലയിൽ

$$\sin \theta = \frac{u}{w}; \theta < \frac{\pi}{2} \text{ ന്റെ}$$

$$\sin \theta < 1 \Rightarrow \frac{u}{w} < 1 \Rightarrow u < w$$

$$\text{രേഖാശാലയിൽ നിന്ന് രേഖാശാലയിൽ} = \frac{d}{w \cos \theta - v}$$

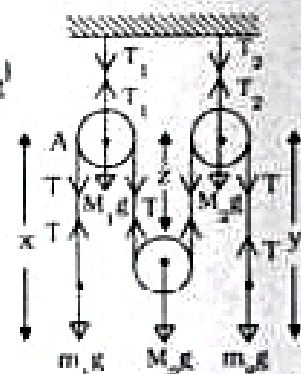
$$= \frac{d}{w \sqrt{1 - \sin^2 \theta} - v} = \frac{d}{\sqrt{w^2 - u^2} - v}$$

82. $x + y + 2z =$ രേഖാശാലയിൽ
രേഖാശാലയിൽ നിന്ന് രേഖാശാലയിൽ

$$\vec{x} + \vec{y} + 2\vec{z} = 0 \text{ ന്റെ}$$

$$\downarrow f_1 = \vec{x}, \downarrow f_2 = \vec{y}$$

$$\text{രേഖാശാലയിൽ } \vec{x} = \frac{(\vec{f}_1 + \vec{f}_2)}{2}$$



$$(a) (m_1^d E) = \downarrow f_1$$

$$(m_1^d E) = \downarrow f_2$$

$$(M_3^d E) = \uparrow \frac{f_1 + f_2}{2}$$

$$F = m_3 g \text{ രേഖാശാലയിൽ}$$

$$\downarrow m_1 g - T = m_1 f_1 \quad \text{--- ①}$$

$$\downarrow m_2 g - T = m_2 f_2 \quad \text{--- ②}$$

$$\uparrow 2T - M_3 g = M_3 \frac{(f_1 + f_2)}{2} \quad \text{--- ③}$$

$$\text{① ന്റെ } f_1 = g - \frac{T}{m_1}$$

$$\text{② ന്റെ } f_2 = g - \frac{T}{m_2}$$

③ ന്റെ രേഖാശാലയിൽ

$$2T - M_3 g = \frac{M_3}{2} \left[g - \frac{T}{m_1} + g - \frac{T}{m_2} \right]$$

$$\frac{4T}{M_3} - 2g = 2g - \frac{T}{m_1} - \frac{T}{m_2} \left(+ \frac{M_3}{2} \text{ ന്റെ} \right)$$

$$T \left[\frac{4}{m_3} + \frac{1}{m_1} + \frac{1}{m_2} \right] = 4g$$

$$T \left[\frac{4m_1 m_2 + M_3 (m_1 + m_2)}{M_3 m_1 m_2} \right] = 4g$$

$$T = \frac{4 m_1 m_2 M_3 g}{4 m_1 m_2 + M_3 (m_1 + m_2)}$$

$$T_1 = 2T + M_1 g; T_2 = 2T + M_2 g$$

രേഖാശാലയിൽ നിന്ന് രേഖാശാലയിൽ

$$T_1 + T_2 = 4T + g (M_1 + M_2)$$

$$= \frac{16 m_1 m_2 M_3 g}{4 m_1 m_2 + M_3 (m_1 + m_2)} + g (M_1 + M_2)$$

രേഖാശാലയിൽ നിന്ന് രേഖാശാലയിൽ



සමස්ත ක්ෂේත්‍රීය නියමය යොදවමු
 $\frac{1}{2}mv^2 - mgr \cos \alpha = \frac{1}{2}mv^2 - mgr \cos \theta$ — ①

$E = mgh$ යොදවමු
 $T - mg \cos \theta = m \frac{v^2}{r}$ — ②

① හි $v^2 = u^2 - 2gr \cos \alpha + 2gr \cos \theta$ — ③

② හි ආදායමක්
 $T = mg \cos \theta + \frac{m}{r}(u^2 - 2gr \cos \alpha + 2gr \cos \theta)$

$T = \frac{m}{r}(u^2 - 2gr \cos \alpha + 3gr \cos \theta)$ — ④

⑤ හි ④ අනුව θ වැඩිවන විට v හා T අවම අගය වශයෙන් ලැබෙන වස්තුය යොදා ගත හැකිවේ.
 $\frac{\pi}{2} < \theta < \pi$ විට $v^2 > 0$ හා $T = 0$ වුවහොත් යම්කිසි

$T = 0$ වන්නේ $\theta = \theta_1$ විටය.

$\cos \theta_1 = \frac{2gr \cos \alpha - u^2}{3gr}$ වේ.

මෙහි $\theta_1 = \cos^{-1} \left[\frac{1}{3} \left(2 \cos \alpha - \frac{u^2}{gr} \right) \right]$ වේ.

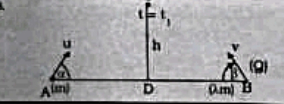
මේ අනුව අංශුව OP වෙතට යයි අත්හිටින බවට
 $\cos^{-1} \left[\frac{1}{3} \left(2 \cos \alpha - \frac{u^2}{gr} \right) \right]$ වන්නේය යැයි සිතමු.

සමස්ත චලිතයෙන් අවම වී ලැබුණා යන්නේ චලිතය අවමයි.

$\frac{\pi}{2} < \theta_1 < \pi$ විට $-1 < \cos \theta_1 < 0$ වැඩිවේ.

මේ හේතු - $1 < \frac{2gr \cos \alpha - u^2}{3gr} < 0$ විය යුතුය.

මෙයින් $gr(3 + 2 \cos \alpha) > u^2 > 2gr \cos \alpha$ වේ යැයි සිතමු.



$t = t_1$ විට අංශු C හි ලබන්නේ AB හි h උසකින්

සිට C උසකටම ගොස් ඇත.

$S = ut + \frac{1}{2}at^2$ යොදවමු

① $h = u \sin \alpha t_1 - \frac{1}{2}gt_1^2$ — ①

② $h = v \sin \beta t_1 - \frac{1}{2}gt_1^2$ — ②

① = ② නිසා $u \sin \alpha = v \sin \beta$ වේ.

$v = u + at$ යොදවමු $(T = t_1)$ අවස්ථාවේ

① $u \sin \alpha = v \sin \beta - gT$ — ③

② $u \sin \alpha = v \sin \beta - gT$ — ④

$u \sin \alpha = v \sin \beta$ නිසා $v = u$ වේ.

$u \sin \alpha = v \sin \beta - gT$ යොදවමු $(T = t_1)$ අවස්ථාවේ

$u \sin \alpha = v \sin \beta - gT$ යොදවමු $(T = t_1)$ අවස්ථාවේ

$u \sin \alpha = v \sin \beta - gT$ යොදවමු $(T = t_1)$ අවස්ථාවේ

$u \sin \alpha = v \sin \beta - gT$ යොදවමු $(T = t_1)$ අවස්ථාවේ

$u \sin \alpha = v \sin \beta - gT$ යොදවමු $(T = t_1)$ අවස්ථාවේ

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$u \sin \alpha = v \sin \beta - gT$ යොදවමු $(T = t_1)$ අවස්ථාවේ

$u \sin \alpha = v \sin \beta - gT$ යොදවමු $(T = t_1)$ අවස්ථාවේ

$u \sin \alpha = v \sin \beta - gT$ යොදවමු $(T = t_1)$ අවස්ථාවේ

$u \sin \alpha = v \sin \beta - gT$ යොදවමු $(T = t_1)$ අවස්ථාවේ

$u \sin \alpha = v \sin \beta - gT$ යොදවමු $(T = t_1)$ අවස්ථාවේ

$u \sin \alpha = v \sin \beta - gT$ යොදවමු $(T = t_1)$ අවස්ථාවේ

$u \sin \alpha = v \sin \beta - gT$ යොදවමු $(T = t_1)$ අවස්ථාවේ

$u \sin \alpha = v \sin \beta - gT$ යොදවමු $(T = t_1)$ අවස්ථාවේ

$u \sin \alpha = v \sin \beta - gT$ යොදවමු $(T = t_1)$ අවස්ථාවේ

$u \sin \alpha = v \sin \beta - gT$ යොදවමු $(T = t_1)$ අවස්ථාවේ

$u \sin \alpha = v \sin \beta - gT$ යොදවමු $(T = t_1)$ අවස්ථාවේ

$u \sin \alpha = v \sin \beta - gT$ යොදවමු $(T = t_1)$ අවස්ථාවේ

$u \sin \alpha = v \sin \beta - gT$ යොදවමු $(T = t_1)$ අවස්ථාවේ

$u \sin \alpha = v \sin \beta - gT$ යොදවමු $(T = t_1)$ අවස්ථාවේ

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$u \sin \alpha = v \sin \beta - gT$ යොදවමු $(T = t_1)$ අවස්ථාවේ

$u \sin \alpha = v \sin \beta - gT$ යොදවමු $(T = t_1)$ අවස්ථාවේ

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$u \sin \alpha = v \sin \beta - gT$ යොදවමු $(T = t_1)$ අවස්ථාවේ

$u \sin \alpha = v \sin \beta - gT$ යොදවමු $(T = t_1)$ අවස්ථාවේ

$u \sin \alpha = v \sin \beta - gT$ යොදවමු $(T = t_1)$ අවස්ථාවේ

$u \sin \alpha = v \sin \beta - gT$ යොදවමු $(T = t_1)$ අවස්ථාවේ

$u \sin \alpha = v \sin \beta - gT$ යොදවමු $(T = t_1)$ අවස්ථාවේ

$u \sin \alpha = v \sin \beta - gT$ යොදවමු $(T = t_1)$ අවස්ථාවේ

$u \sin \alpha = v \sin \beta - gT$ යොදවමු $(T = t_1)$ අවස්ථාවේ

$u \sin \alpha = v \sin \beta - gT$ යොදවමු $(T = t_1)$ අවස්ථාවේ

$u \sin \alpha = v \sin \beta - gT$ යොදවමු $(T = t_1)$ අවස්ථාවේ

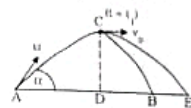
iii) P අංශුව එළඹී වැටීමේ උස CD = h කිසි.

$v^2 = u^2 + 2as$ යොදවමු

$O = u^2 \sin^2 \alpha - 2gh$

$h = \frac{u^2 \sin^2 \alpha}{2g}$

සාදන ක්ෂේත්‍ර E හි දී සමතුලිතතාවය යොදවමු.



C → E චලිතය සලකමු.

$S = ut + \frac{1}{2}at^2$ යොදවමු

$\frac{u^2 \sin^2 \alpha}{2g} = 0 + \frac{1}{2}gt^2$

$t_2 = \frac{u \sin \alpha}{g} = t_1$ වේ.

ලැබුණ පසු P හි චලිතය සලකමු.

$AD = u \cos \alpha \times t_1 = u \cos \alpha \times \frac{u \sin \alpha}{g}$

$DE = v_0 \times t_2$ (ලැබුණ පසු චලිතය)

$AE = AD + DE$ වුවහොත්

$AE = \frac{u^2 \sin \alpha \cos \alpha}{g} + \frac{(1-\lambda)}{(1+\lambda)} u \cos \alpha \times \frac{u \sin \alpha}{g}$

$AE = \frac{u^2 \sin 2\alpha}{g(1+\lambda)}$

P හි සමතුලිතතාව Q හි සමතුලිතතාවය යොදවමු.

$\lambda \rightarrow 0$ වේ.

එවිට $AE = \frac{u^2 \sin 2\alpha}{g}$ වන්නේ E හි වේ.

Q හි සමතුලිතතාව P හි සමතුලිතතාවය යොදවමු.

$\lambda \rightarrow \infty$ වේ.

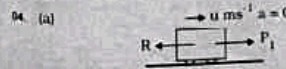
එවිට $AE = 0$, එනම් E = A වේ.

P හි Q හි සමතුලිතතාවය යොදවමු $\lambda = 1$

එවිට $AE = \frac{u^2 \sin 2\alpha}{2g} = \frac{\Delta h}{2}$

එවිට E යනු AB හි මධ්‍ය ලක්ෂ්‍යයයි.

$\therefore AB = \frac{u^2 \sin 2\alpha}{g}$ වැඩිවේ.

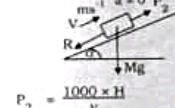


සමතුලිතතාවය යොදවමු $P_1 = \frac{1000 \times H}{u}$

$E = ma$ යොදවමු

$\rightarrow P_1 - R = M \times 0$

$R = \frac{1000 \times H}{u}$



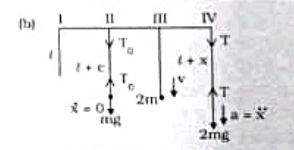
$P_2 = \frac{1000 \times H}{v}$

$P_2 - R - Mg \sin \alpha = 0$

$\frac{1000H}{v} - \frac{1000H}{u} = Mg \sin \alpha$

$1000H \left(\frac{u-v}{uv} \right) = Mg \sin \alpha$

$H = \frac{uv Mg \sin \alpha}{1000(u-v)}$ kW



ii) අවස්ථාවේ, λ යනු සමතුලිතතාවය යොදවමු.

$T_0 = mg$ ($\because \vec{x} = 0$ නිසා)

$T_0 = \frac{\Delta x}{t}$

$\frac{\Delta x}{t} = mg$

$\lambda = \frac{mg}{c}$

iii) අවස්ථාවේ, සමතුලිතතාවය යොදවමු.

$\psi m \times 0 + m \times u = 2m \times v$

u යනු Q අංශුව c උසකින් වැටීමේ ලබන වේගය වේ.

$u^2 = 0 + 2gc$

$v = \frac{u}{2} = \sqrt{\frac{gc}{2}}$

iv) අවස්ථාවේ,

$T = \frac{\Delta x}{t} = \frac{Mmg}{c} \times \frac{x}{\lambda} = \frac{Mmg}{c}$

$E = mgh$ යොදවමු

$2mg - T = 2m \times \ddot{x}$

සාදන ක්ෂේත්‍ර E හි දී සමතුලිතතාවය යොදවමු.

$$2 \text{ mg} - \frac{m \dot{x}}{c} = 2 \text{ m} \ddot{x}$$

$$\ddot{x} = \frac{-g}{2c} x + g$$

$$\ddot{x} + \omega^2 x - 2\omega^2 c = 0 \quad (\because \omega^2 = \frac{g}{2c})$$

$$\ddot{x} + \omega^2 (x - 2c) = 0$$

$$x = 2c + a \cos \omega t + b \sin \omega t \quad \text{--- (1)}$$

$$t = 0 \text{ විට } x = c \text{ වේ}$$

$$c = 2c + a \Rightarrow a = -c$$

⑥. t විෂයයේ අවකලනය

$$\dot{x} = -a\omega \sin \omega t + b\omega \cos \omega t \quad \text{--- (2)}$$

$$t = 0 \text{ විට } \dot{x} = \frac{u}{2} = \sqrt{\frac{g}{2c}} \text{ වේ}$$

$$\sqrt{\frac{g}{2}} = b\omega \Rightarrow b = \frac{u}{2\omega} = \frac{u}{2\sqrt{\frac{g}{2c}}} = \frac{u\sqrt{2c}}{2\sqrt{g}}$$

$$\text{⑦. } \dot{x} = c\omega \sin \omega t + c\omega \cos \omega t$$

$$\dot{x} = c\omega (\sin \omega t + \cos \omega t)$$

$$t = t_1 \text{ විට } \dot{x} = 0 \text{ වේ නම් } (g \text{ අඩු කිරීම})$$

$$0 = c\omega (\sin \omega t_1 + \cos \omega t_1)$$

$$\sin \omega t_1 = -\cos \omega t_1$$

$$\tan \omega t_1 = -1$$

$$\omega t_1 = \frac{3\pi}{4}$$

$$t_1 = \frac{3\pi}{4\omega} = \frac{3\pi}{4} \times \frac{1}{\sqrt{\frac{g}{2c}}} = \frac{3\pi}{4} \sqrt{\frac{2c}{g}}$$

එවිට විස්ථාප

$$\text{⑧. } x = 2c + c \cos \left(\omega \cdot \frac{3\pi}{4} \right) + c \sin \left(\omega \cdot \frac{3\pi}{4} \right)$$

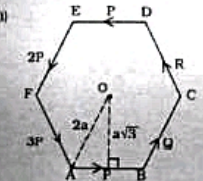
$$x = 2c - c \cos \frac{3\pi}{4} + c \sin \frac{3\pi}{4}$$

$$= 2c - c \left(-\frac{1}{\sqrt{2}} \right) + c \left(\frac{1}{\sqrt{2}} \right)$$

$$= 2c + \sqrt{2} c$$

$$\text{විස්ථාප} = \sqrt{2} c (1 + \sqrt{2}) \quad (x = 0 \text{ වන})$$

os. (a) (i)



ද්‍රව්‍යය මත ප්‍රතික්‍රියාවක් ඇතැයි සිතමු.

$$G = 0 \text{ නම් } \sum \tau = 0 \text{ වේ.}$$

මේ සදහා විස්ථාපය 0 වීමේ දිනේ ඇති (AB සහ AE) රේඛාවේ විස්ථාපය සමානව වීම අවශ්‍යය.

$$\rightarrow P + Q \cos 60^\circ - R \cos 60^\circ - P = 0$$

$$2P \cos 60^\circ + 3P \cos 60^\circ = 0$$

$$R - Q = P \quad \text{--- (1)}$$

$$\uparrow (Q + R - 2P - 3P) \cos 30^\circ = 0$$

$$Q + R = 5P \quad \text{--- (2)}$$

$$\text{① + ② } R = 3PN \quad \text{--- (3)}$$

$$Q = 2PN \quad \text{--- (4)}$$

$$\text{ප්‍රතික්‍රියා ප්‍රතික්‍රියා සමතුලිත O වෙතින් දුර මගින්}$$

$$(P + Q + R + P + 2P + 3P) a \sqrt{3} = 0$$

$$= (17P + 3P + 2P) a \sqrt{3}$$

$$= 12 \sqrt{3} a PN \text{ m}$$

$$\text{--- (5)}$$

$$\text{--- (6)}$$

$$\text{--- (7)}$$

$$\text{--- (8)}$$

$$\text{--- (9)}$$

$$\text{--- (10)}$$

$$\text{--- (11)}$$

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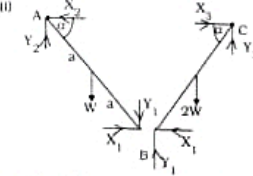
B වටා ප්‍රතික්‍රියාව

$$T \times AB \sin \alpha = G \quad ; \quad AB = a \cot \frac{\alpha}{2}$$

$$T \times a \cot \frac{\alpha}{2} \sin \alpha = G$$

$$\frac{\mu W a}{(\cos \alpha + \mu \sin \alpha)} (1 + \cos \alpha) = G$$

os. (a) (i)



එක් එක් දණ්ඩේ සමතුලිතතාව සඳහා ප්‍රතික්‍රියාව

$$A \text{ වටා } AB \text{ ට}$$

$$W \times a \cos \alpha + Y_1 \times 2a \cos \alpha$$

$$- X_1 \times 2a \sin \alpha = 0 \quad \text{--- (1)}$$

$$C \text{ වටා } CB \text{ ට}$$

$$2W \times a \cos \alpha - Y_1 \times 2a \cos \alpha$$

$$- X_1 \times 2a \sin \alpha = 0 \quad \text{--- (2)}$$

$$\text{① + ② න්}$$

$$3W \cos \alpha = 4X_1 \sin \alpha$$

$$X_1 = \frac{3W \cot \alpha}{4}$$

$$\text{① - ② න්}$$

$$-W \cos \alpha + 4Y_1 \cos \alpha = 0$$

$$Y_1 = \frac{W}{4}$$

$$\text{--- (3)}$$

$$\text{--- (4)}$$

$$\text{--- (5)}$$

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$$\text{--- (36)}$$

AB සමතුලිතතාවය සඳහා

$$\rightarrow X_1 = X_2 = \frac{3W \cot \alpha}{4}$$

$$\uparrow Y_2 = W + Y_1 = \frac{5W}{4}$$

$$BC \text{ සමතුලිතතාවය සඳහා}$$

$$\rightarrow X_3 = X_1 = \frac{3W \cot \alpha}{4} = X_2$$

$$\uparrow Y_3 = 2W - Y_1 = \frac{7W}{4}$$

$$\frac{5W}{4} \times \frac{7W}{4} = \frac{3W \cot \alpha}{4} \times \frac{3W \cot \alpha}{4}$$

$$35 = 9 \cot^2 \alpha$$

$$\tan^2 \alpha = \frac{9}{35}$$

$$\tan \alpha = \frac{3}{\sqrt{35}}$$

$$\text{--- (37)}$$

$$\text{--- (38)}$$

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$$\text{--- (84)}$$

$$\text{--- (85)}$$

(b)

ලකුණ	මධ්‍ය අගය	අපගමනය (d_i)	u_i	f_i	$f_i u_i$	$f_i u_i^2$
30 - 34	32	-15	-3	5	-15	45
35 - 39	37	-10	-2	10	-20	40
40 - 44	42	-5	-1	15	-15	15
45 - 49	47	0	0	30	0	0
50 - 54	52	+5	1	5	+5	5
55 - 59	57	+10	2	5	+10	20
				70	35	125

$$(i) \text{ සමයුග්‍මය } \bar{x} = A + C \left(\frac{\sum f_i u_i}{\sum f_i} \right)$$

$$= 47 + \frac{5(-35)}{70} = 44.5$$

$$\text{සමයුග්‍මය } \sigma_1^2 = C^2 \left[\frac{\sum f_i u_i^2}{\sum f_i} - \left(\frac{\sum f_i u_i}{\sum f_i} \right)^2 \right]$$

$$= 25 \left[\frac{125}{70} - \left(\frac{-35}{70} \right)^2 \right]$$

$$\bar{x} = 25 \left[\frac{25}{14} - \left(\frac{1}{2} \right)^2 \right] = \frac{25 \times 43}{28}$$

$$= 38.39$$

(ii) (a) I සමයුග්‍මය සඳහා

$$38 = \frac{170 \times 44.5 + (30 \times \bar{y})}{70 + 30}$$

$$(\because m = 70, n = 30, \bar{x} = 44.5 \text{ සිට})$$

$$\bar{y} = 22.83$$

(a) III සමයුග්‍මය සඳහා

$$\sigma^2 = \frac{1}{m+n} (m(\sigma_2^2 + d_2^2) + n(\sigma_1^2 + d_1^2))$$

$$m = 30, n = 70, \sigma_1^2 = 38.39,$$

$$d_2 = \bar{y} - \bar{x} = 22.83 - 38 = -15.17$$

$$d_1 = \bar{x} - \bar{z} = 44.5 - 38 = 6.5; \sigma^2 = 144$$

$$144 = \frac{1}{30+70} (30(\sigma_2^2 + (-15.17)^2) + 70(38.39 + (6.5)^2))$$

$$14400 = 30\sigma_2^2 + 6903.9 + 2687.3 + 2957.5$$

$$1851.3 = 30\sigma_2^2$$

$$\sigma_2^2 = 61.71$$

*** **

